# Approximating Dense Cases of Covering Problems

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TR-96-059

December 1996

#### Abstract

We study dense cases of several covering problems. An instance of the set cover problem with m sets is dense if there is  $\epsilon>0$  such that any element belongs to at least  $\epsilon m$  sets. We show that the dense set cover problem can be approximated with the performance ratio  $c\log n$  for any c>0 and it is unlikely to be NP-hard. We construct a polynomial-time approximation scheme for the dense Steiner tree problem in n-vertex graphs, i.e. for the case when each terminal is adjacent to at least  $\epsilon n$  vertices. We also study the vertex cover problem in  $\epsilon$ -dense graphs. Though this problem is shown to be still MAX-SNP-hard as in general graphs, we find a better approximation algorithm with the performance ratio  $\frac{2}{1+\epsilon}$ . The superdense cases of all these problems are shown to be solvable in polynomial time.

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### 1 Dense Set Cover Problem

We start with the Dense Set Cover Problem. Let  $X = \{x_1, ..., x_k\}$  be a finite set and  $P = \{p_1, ..., p_m\} \subseteq 2^X$  be a family of its subsets. The Set Cover Problem (SCP) asks for a minimum size sub-family M of P such that  $X \subseteq \bigcup \{p | p \in M\}$ .

The greedy heuristic gives 1 + lnk approximation for SCP [5]. Moreover, SCP cannot be approximated to within less than  $\ln k$ -factor unless  $NP \subseteq DTIME[n^{loglogn}]$  [6].

The B-sparse SCP has a constant upper bound B>1 on the number of sets in P which cover the same element of X. The Vertex Cover Problem is a well-known representative of B-sparse SCP (B=2). There is a simple B-approximation algorithm for this problem. From the other side, the B-sparse SCP is MAX SNP-complete.

In an  $\epsilon$ -dense SCP, any element of X belongs to at least  $\epsilon|P|$  sets for some  $\epsilon < 1$ .

We will analyze the greedy heuristic applied to  $\epsilon$ -dense SCP. This heuristic repeatedly choose a maximum size set in P, remove its elements from X and all other sets in P. All chosen sets form the output set cover Greedy.

**Lemma 1** The size of Greedy is at most  $\log_{1/(1-\epsilon)} k$ .

**Proof.** At first we will show that the maximum size of a set in P is at least  $\epsilon k$ . Consider a bipartite graph  $G = (P \cup X, E)$  where  $x \in X$  and  $p \in P$  are adjacent if and only if  $x \in p$ . The degree of any  $x \in X$  is at least  $\epsilon m$ , so the number of edges in this graph is at least  $\epsilon mk$  and, therefore, there is a set  $p \in P$  with degree at least  $\epsilon m$ .

Each iteration of the greedy heuristic does not decrease density, since all elements which belong to the chosen set are removed from X. So the size of X after the ith iteration is at most  $(1 - \epsilon)^i k \diamondsuit$ 

This lemma shows that the size of the optimal set cover is  $O(\log k)$ . So we cannot expect that the  $\epsilon$ -dense SCP is NP-complete, since a simple  $O(m^{O(\log k)})$ -time exhaustive search chooses the optimal solution.

**Theorem 1** Unless  $NP \subseteq DTIME[n^{\log n}]$ , the  $\epsilon$ -dense SCP is not NP-complete.

Note that  $O(\log k)$  is the tight bound for the performance ratio of the greedy heuristic applied to  $\epsilon$ -dense SCP. To show this for  $\epsilon = \frac{1}{2}$ , we can construct an instance of this problem with the size of optimal solution of  $O(\log k)$  and then add two sets A and B such that  $A \cup B = X$ ,  $A \cap B = \emptyset$ . On the other hand, unlike to the general case of SCP, we may decrease the constant factor as far as we want.

**Lemma 2** For any c>0 and  $1>\epsilon>0$ , there is a  $c\ln k$ -approximation algorithm for  $\epsilon$ -dense SCP.

**Proof.** Indeed, let transform an instance of  $\epsilon$ -dense SCP to an instance of  $(1-(1-\epsilon)^2)$ -dense SCP in the following way. Consider a family  $P^2 = \{p \cup q : p, q \in P\}$ . It is easy to see that any solution for SCP with the family  $P^2$  gives a solution for initial SCP. An  $\epsilon$ -density means that at most  $(1-\epsilon)m$  sets do not contain a given element of X. But then at most  $(1-\epsilon)^2m^2$  sets in  $P^2$  do not contain a given element of X.

Lemma 1 implies that such transformation decrease the performance ratio of the greedy algorithm twice.  $\Diamond$ 

Theorem 1 arises the following two open problems:

**Problem 1** Can  $\epsilon$ -dense SCP be solved in polynomial time?

**Problem 2** Can  $\epsilon$ -dense SCP be approximated in polynomial time to within constant factor?

Further densification leads to polynomial solvability of SCP. The  $\delta$ -superdense SCP is the case of SCP where each element of X is covered by at least  $m - o(m^{\delta})$  sets of P for some  $\delta < 1$ .

**Theorem 2** The  $\delta$ -superdense SCP can be solved in polynomial time.

**Proof.** Let each element of X is covered by at least  $m - \gamma m^{\delta} = m(1 - \gamma m^{\delta-1})$  sets of P for some  $\gamma < m^{1-\delta}$ . By Lemma 1 for  $\epsilon = 1 - \gamma m^{\delta-1}$ , the size of optimal solution is at most

$$\log_{\gamma^{-1}m^{1-\delta}} k = \frac{1}{(1-\delta)(1-\log_m \gamma)} \log_m k.$$

Thus, exhaustive search for finding an exact solution has at most  $k^{((1-\delta)\delta)^{-1}}$  cases to consider.  $\diamondsuit$ 

# 2 Dense Steiner Tree Problem

Consider a connected graph G=(V,E) with a terminal set  $S\subseteq V$ . The Steiner Tree Problem (STP) asks for a minimum size tree within G which spans all terminals from S. Further, d(F) denotes the length of a graph F, |S|=k and |V|=n. A well-known minimum spanning tree heuristic (MSTH) [9] finds a minimum spanning tree M of a weighted complete graph G'=(S,E',c), where the weight of any edge equals to the length of the shortest path between its ends in G. Then MSTH replaces all edges of M with the corresponding paths in G and extracts a tree from the subgraph obtained.

An optimal Steiner tree contains also non-terminals. Each such vertex of degree at least 3 is called a *Steiner point*. It is easy to see that there are at most k-2 Steiner points. Using MSTH we can find an optimal Steiner tree if we add all Steiner points to the terminal set.

**Remark 1** An optimal Steiner tree can be found exactly in  $O(n^k)$  time.

MSTH gives 2-approximation for STP [9] and the best up-today polynomial-time approximation guarantee is about 1.644 [7]. From the other side, STP is known to be MAX SNP - complete [4].

In the B-sparse STP the degree of any vertex is bounded by a constant B. It is known that STP in the rectilinear metric (a sub-case of 4-sparse STP) is NP-complete but the question whether it is MAX SNP-hard or not is still open.

In an  $\epsilon$ -dense instance of STP (for some  $\epsilon < 1$ ) any terminal has at least  $\epsilon n$  neighbors outside S.

Note that for  $\epsilon > \frac{1}{2}$ ,  $\epsilon$ -dense STP is a sub-case of Network STP with distances 1 and 2 which is still MAX SNP-complete [4]. The Rayward-Smith heuristic [8] was proposed for the latter problem in [4]. It achieves a better approximation guarantee  $(\frac{4}{3})$  then MSTH

which has the tight bound 2 as for the general case. MSTH also does not differ the dense and general case of STP.

If the number of terminals is small enough, i.e.  $k \leq \frac{1}{\epsilon}$ , then we can find an exact solution in polynomial time. Otherwise, we apply to the dense STP the following variant of Rayward-Smith heuristic (or the greedy algorithm [10]).

#### Algorithm DSTP

- (0)  $SP \leftarrow \emptyset$ ;  $\mathcal{C} \leftarrow \{\{s\} : s \in S\}$  (1) while  $|\mathcal{C}| > \frac{1}{\epsilon}$  do find  $v \in V \setminus S$  with the maximum size of  $D(v) = \{C \in \mathcal{C} : C \text{ contains a neighbor of } v\}$   $SP \leftarrow SP \cup v$ ;  $\mathcal{C} \leftarrow \mathcal{C} \setminus D(v) \cup \{\cup_{C \in D(v)} C\}$ ;
- (2) find an optimal Steiner tree T for a terminal set  $S \cup SP$ .

Let C consist of sets  $C_1, ..., C_r$  after Step (1) of Algorithm DSTP. Let add edges between all terminals of the same set  $C_i, i = 1, ..., r$ . The length of the optimal Steiner tree in the graph G' obtained cannot be longer than in G. There is an optimal Steiner tree OPT' in G' containing spanning trees  $M_i$  for each set  $C_i, i = 1, ... r$ . If we contract any such tree  $M_i$  to a vertex, then OPT' appears to be an optimal Steiner tree  $M_0$  spanning vertices corresponding to  $C_i$ . Thus, the edge set of OPT' is a union of edges of  $M_i, i = 0, 1, ..., r$ .

Algorithm DSTP constructs some Steiner trees  $M'_i$  in G for terminals of  $C_i$  (step (1)) and then finds the shortest tree  $M'_0$  spanning  $M'_i$ , i=1,...,r (step (2)).  $M'_0$  cannot be longer that  $M_0$ , since  $M_0$  also spans  $M'_i$ . Remark 1 implies that an exhaustive search in Step (2) can be executed in time  $O(n^{1/\epsilon})$ .

An approximation ratio of Algorithm DSTP is at most

$$\frac{\sum_{i=0}^{r} d(M_i')}{\sum_{i=0}^{r} d(M_i)} \le \frac{\sum_{i=1}^{r} d(M_i')}{\sum_{i=1}^{r} d(M_i)} = \frac{k-r+|SP|}{k-r} \le 1 + \frac{|SP|}{k-\frac{1}{\epsilon}}.$$
 (1)

The size of SP equals to the number of iterations in Step (1). Each iteration of (1) decreases the size of  $\mathcal{C}$  by at least  $\epsilon |\mathcal{C}| - 1$ . Thus, after *i*-th iteration  $|\mathcal{C}| \leq (k - \frac{1}{\epsilon})(1 - \epsilon)^i + \frac{1}{\epsilon}$ . The procedure (1) interrupts when  $|\mathcal{C}| < \frac{1}{\epsilon} + 1$ , so

$$|SP| \le \log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon}).$$

Thus, (1) implies the following

**Lemma 3** An approximation ratio of Algorithm DSTP is at most

$$1 + \frac{\log_{1/(1-\epsilon)}(k - \frac{1}{\epsilon})}{k - \frac{1}{\epsilon}} \diamondsuit$$

Given an arbitrary approximation ratio  $1 + \gamma$ ,  $\gamma > 0$ , our strategy is to solve exactly in polynomial time (for fixed  $\epsilon$  and  $\gamma$ ) instances of DSTP with small number of terminals, i.e.

when k satisfies the following inequality

$$\frac{\log_{1/(1-\epsilon)}(k-\frac{1}{\epsilon})}{k-\frac{1}{\epsilon}} \le \gamma.$$

If the number of terminals is sufficiently big, then we apply Algorithm DSTP. Thus we obtain the following

**Theorem 3** There is a polynomial-time approximation scheme for the  $\epsilon$ -dense STP.  $\Diamond$ 

It is not difficult to see that there is a polynomial time reduction of the  $\epsilon$ -dense SCP to the  $\epsilon$ -dense STP and vice versa, thus, the problem of polynomial time solvability of  $\epsilon$ -dense STP is equivalent to Problem 1.

Similarly to SCP, we define  $\delta$ -superdense STP to be the case of STP where any terminal has at least  $n - o(n^{\delta})$  neighbors outside S.

Corollary 1 The  $\delta$ -superdense STP can be solved exactly in polynomial time.

# 3 Dense Vertex Cover Problem

**Vertex Cover Problem (VCP).** Given a graph G = (V, E), find a minimum size vertex set  $OPT \subseteq V$  such that at least one end of any edge belongs to OPT.

The following algorithm is suggested for VCP in  $\epsilon$ -dense graphs, i.e., in graphs where any vertex has at least  $\epsilon n$  neighbors for some  $\epsilon > 0$  (|V| = n). Let O(v) denote the set of neighbors of a vertex v, G(V') denote a subgraph induced by a vertex set  $V' \subseteq V$  and 2VC denote the well-known 2-approximation algorithm for VCP.

### Algorithm DVC

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\begin{array}{l} \text{for all } v \in V \\ \text{do } V' \leftarrow V \setminus (O(v) \cup \{v\}); \\ \text{find a vertex cover } VC(v) \text{ for } G(V') \text{ using 2VC}; \\ VC(v) \leftarrow O(v) \cup VC(v); \\ APPR \leftarrow arg \min_{v \in V} |VC(v)|. \end{array}
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Let  $v \notin OPT$ . Then  $O(v) \subseteq OPT$  since all edges incident to v should be covered by OPT. Moreover, O(v) covers all edges between O(v) and the corresponding V'. So the rest of vertices of OPT cover the edges of G(V').

Let OPT' = OPT - O(v). The output vertex cover of 2VC applied to V' has a size at most min  $\{2|OPT'|, |V'|\}$ . So the approximation ratio can be bounded as follows.

$$\frac{|APPR|}{|OPT|} \le \frac{|O(v)| + \min\{2|OPT'|, |V'|\}}{|O(v)| + |OPT'|} \le \min\{\frac{|O(v)| + 2|OPT'|}{|O(v)| + |OPT'|}, \frac{n}{|O(v)| + |OPT'|}\}$$
If  $2|OPT'| \le (1 - \epsilon)n$ , then

$$\frac{|APPR|}{|OPT|} \le \frac{\epsilon n + 2|OPT'|}{\epsilon n + |OPT'|} = 2 - \frac{1}{1 + \frac{|OPT'|}{\epsilon n}}$$

Thus, the more |OPT'| corresponds to the more bound for the approximation ratio. Therefore,

$$\frac{|APPR|}{|OPT|} \le 2 - \frac{1}{1 + \frac{0.5(1 - \epsilon)n}{\epsilon n}} = \frac{2}{1 + \epsilon}.$$

If  $2|OPT'| \geq (1-\epsilon)n$ , then we obtain the same bound for the approximation ratio as follows

$$\frac{|APPR|}{|OPT|} \le \frac{n}{\epsilon n + 0.5(1 - \epsilon)n} = \frac{2}{1 + \epsilon}.$$

**Theorem 4** The algorithm DVC has an approximation ratio at most  $\frac{2}{1+\epsilon}$  for  $\epsilon$ -dense graphs.

**Theorem 5** The  $\epsilon$ -dense Vertex Cover Problem is MAX SNP-hard.

**Proof.** (Sketch.) Starting with an instance of the Vertex Cover Problem in a graph G with n vertices we dencify it joining all vertices of a clique of size  $\frac{\epsilon}{1-\epsilon}n$  with all vertices of G. The resulting graph is  $\epsilon$ -dense and, therefore, if we have an  $\alpha$ -approximation for DVC, then the reduction above gives  $\alpha(1+\epsilon)$ -approximation algorithm for the general problem which is MAX SNP-hard.  $\diamond$ 

Further densification (as for SCP and STP) leads to decreasement of approximation complexity.

We say that an instance of VCP is  $\delta$ -superdense if the degree of any vertex is at least  $n - o(n^{\delta})$ . Theorem 4 implies

Corollary 2 The  $\delta$ -superdense VCP has a polynomial-time approximation scheme.

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