



# Experimental Design for Machine Learning on Multimedia Data

## Lecture 8

Prof. Gerald Friedland,  
[fractor@eecs.berkeley.edu](mailto:fractor@eecs.berkeley.edu)



# Today

- Answers to Questions
- More on Audio Properties
- Audio Analysis: Features
- Some frameworks and tools to work with sound



## Q&A (2012)

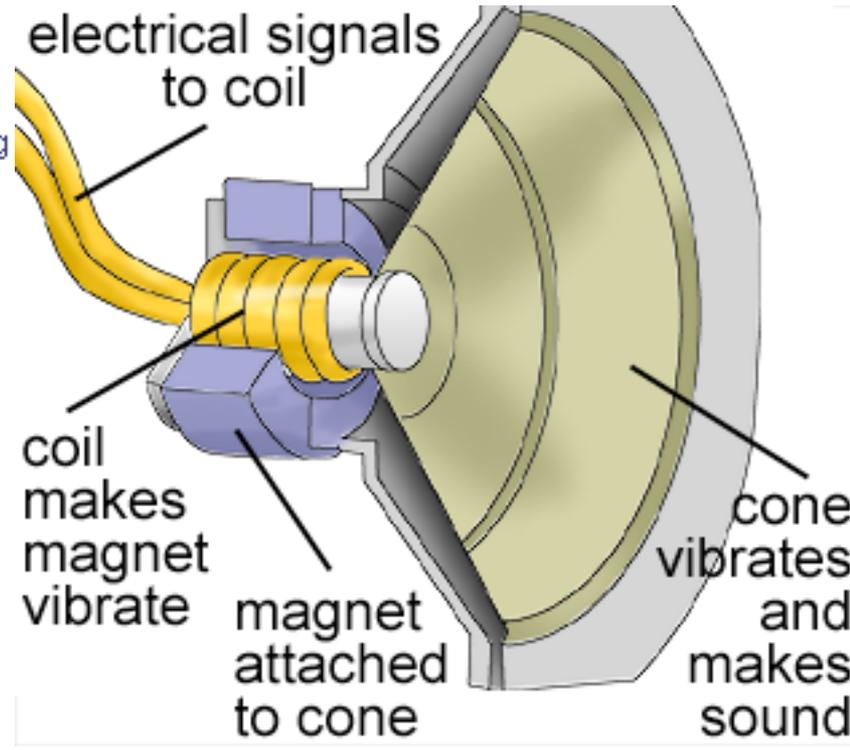
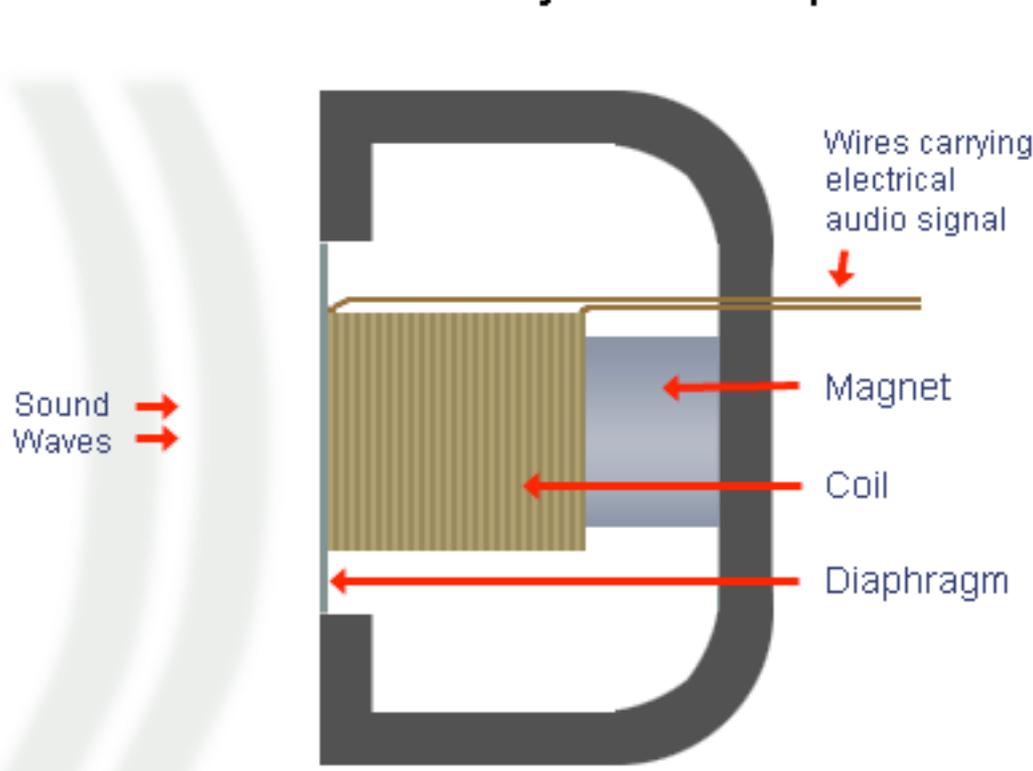
Why is the CD sampling rate 44100Hz and not just 44000?

- Because it is dividable by both 25 video frames per second (PAL) and 30 fps (NTSC)



# Loudspeakers vs Microphones

### Cross-Section of Dynamic Microphone

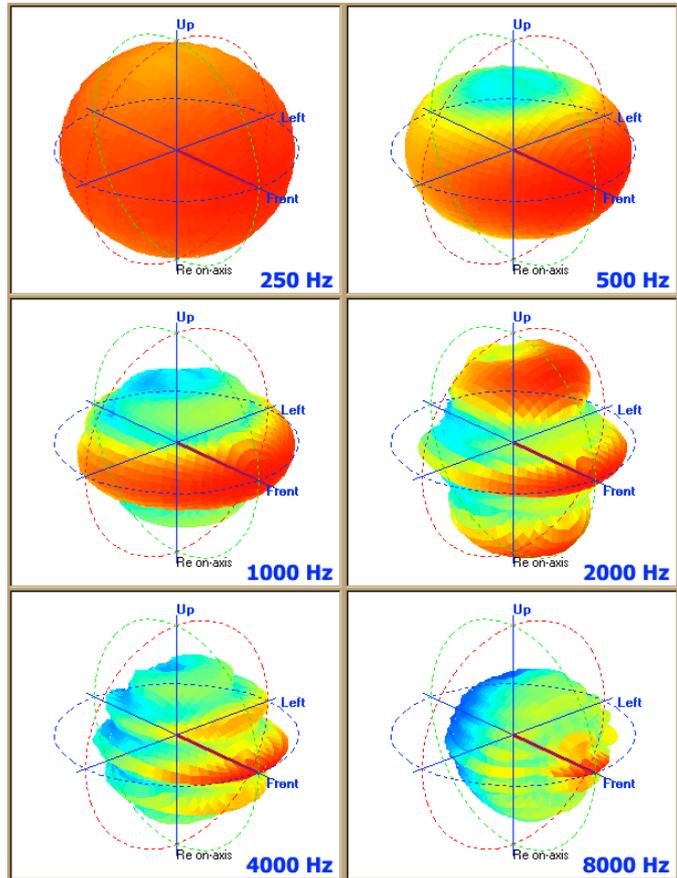


Source: <http://www.physics.org>

Source: <http://www.mediacollege.com/audio/microphones/dynamic.html>



# Loudspeaker Characteristics



Frequency dependent!  
(As are the response patterns of Microphones!)



# Useful Filters

- Low-, High-, Band-pass, Graphic Equalizer
- Dynamic Range Compression
- Filter by Example (before Neural Networks):  
Spectral Subtraction, Wiener Filter
- Handling Multiple Channels



# Remember: Fourier Transform

DFT

$$X_k = \sum_{n=0}^{N-1} x_n e^{-\frac{2\pi i}{N}kn} \quad k = 0, \dots, N - 1$$

iDFT

$$x_n = \frac{1}{N} \sum_{k=0}^{N-1} X_k e^{\frac{2\pi i}{N}kn} \quad n = 0, \dots, N - 1.$$

More Information: “Introduction to Multimedia Computing”, Draft Chapter 8



# Remember: Fast Fourier Transform

```
// Input: A number N of samples X. N must be an integer power of two.
// s the stride
// Output: The Discrete Fourier Transform of X in the array Y.
FFT(X, N, s)
IF (N==1) THEN
Y[0]:=X[0] // Trivial size-1 case: Sample = DC coefficient
ELSE
Y[0,...,N/2]:=FFT(X,N/2,2*s) // DFT of (X[0],X[2s},X[4s},...)
Y[N/2,...,N-1]:=FFT(X[s,...,N-1],N/2,2*s)
// DFT of (X[s],X[s+2s},X[s+4s},...)
FOR k:=0 TO N/2 // Combine the two halves into one
t:=Y[k]
Y[k]:=t+exp(-2*pi*k/N)*Y[k=N/2]
Y[k+N/2]:=t-exp(-2*pi*k/N)*Y[k=N/2]
FFT := Y
```

More Information: “Introduction to Multimedia Computing”, Draft Chapter 8



# Remember: Convolution Theorem

Let  $f$  and  $g$  be two functions and  $f * g$  their convolution. Then:

$$\mathcal{F}\{f * g\} = \mathcal{F}\{f\} \cdot \mathcal{F}\{g\}$$

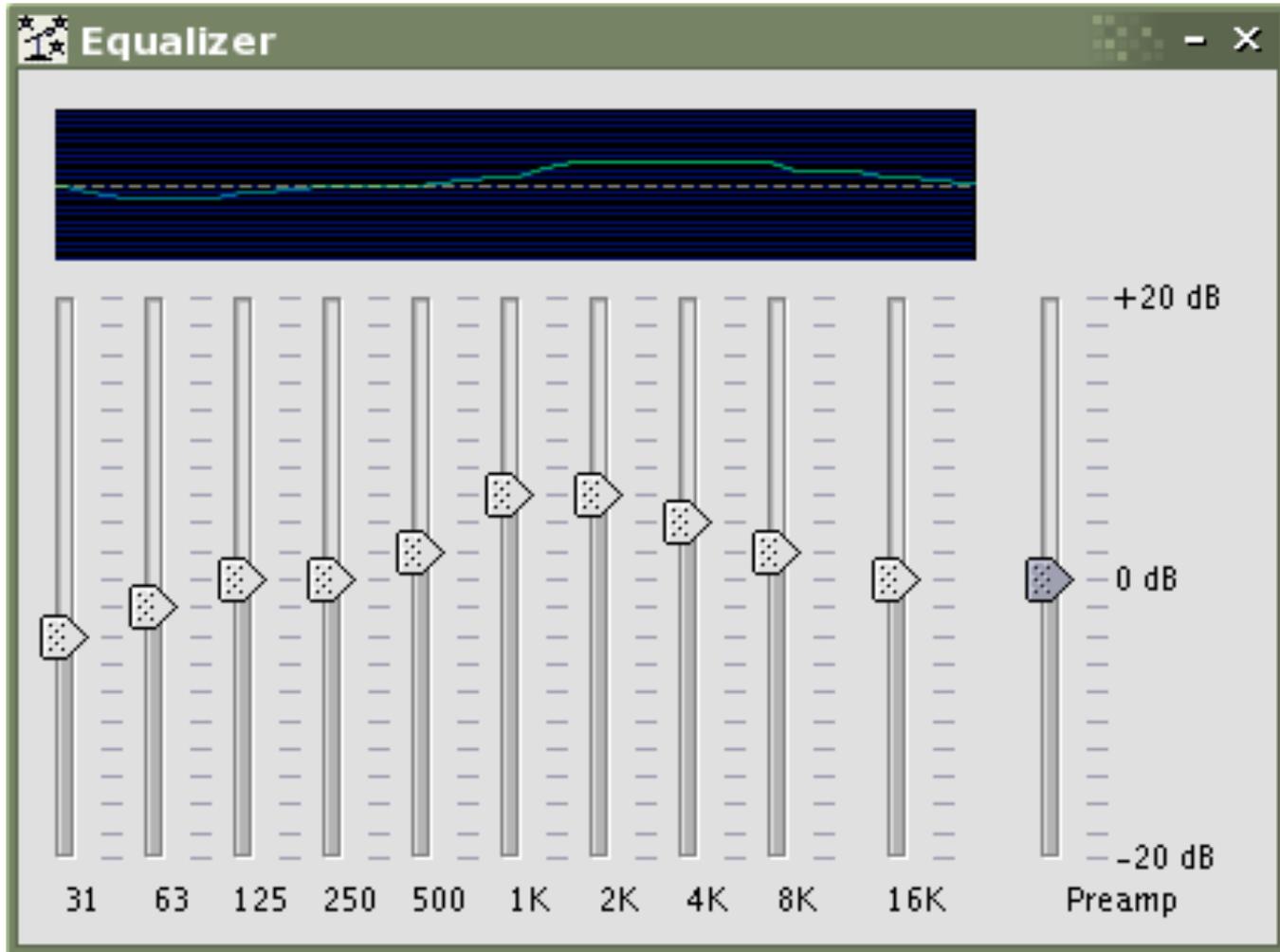
$$\mathcal{F}\{f \cdot g\} = \mathcal{F}\{f\} * \mathcal{F}\{g\}$$

$$f * g = \mathcal{F}^{-1}\{\mathcal{F}\{f\} \cdot \mathcal{F}\{g\}\}$$

More Information: “Introduction to Multimedia Computing”, Draft Chapter 8

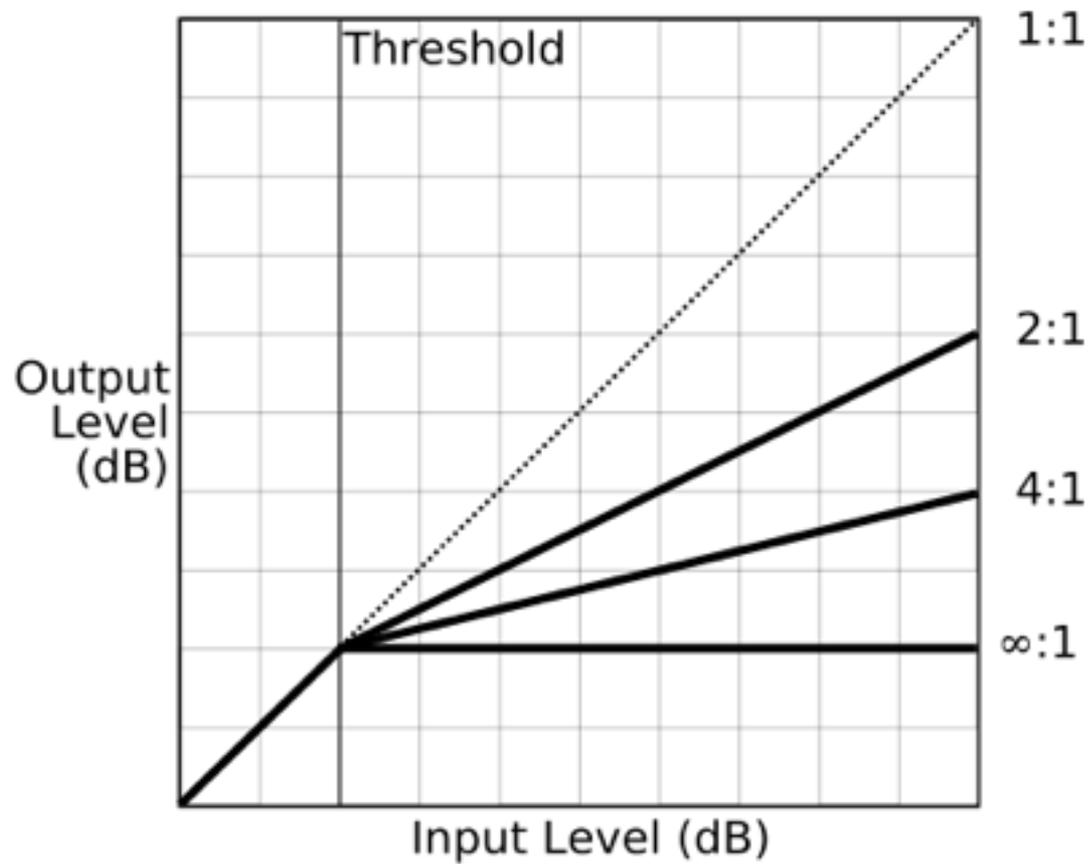


# Bandpass Filters



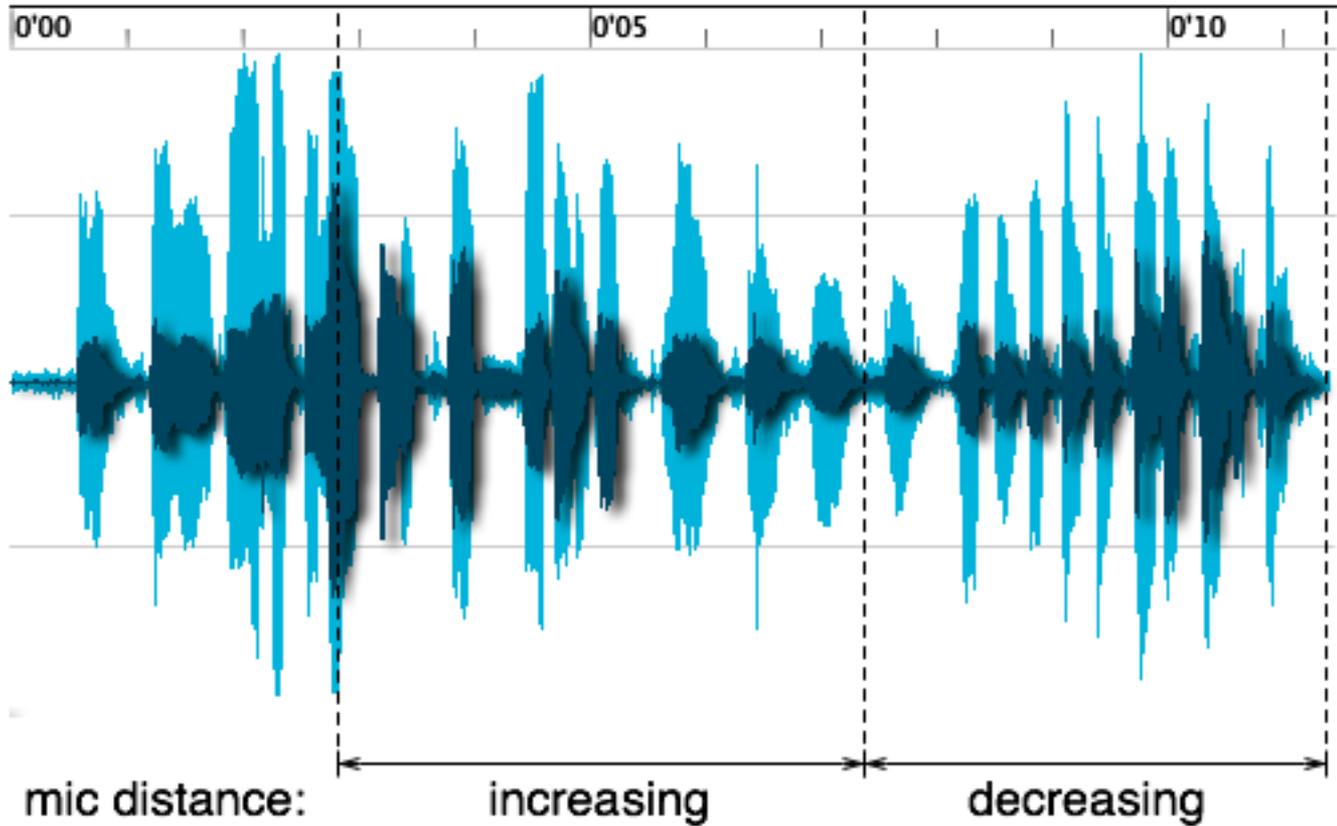


# Dynamic Range Compression





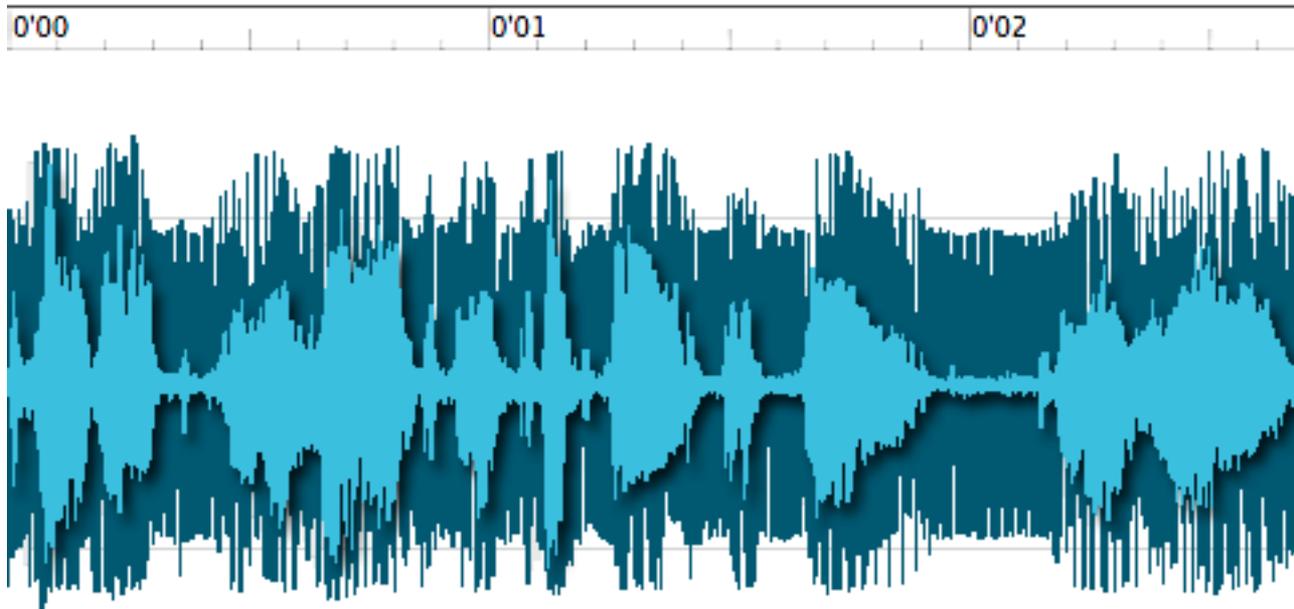
# Dynamic Range Compression



Dark blue: Original, Light Blue: Dynamic Range Compressed



# Filter by Example: Spectral Subtraction



Dark blue: Original with humming noise, Light blue: Corrected using spectral subtraction of humming.



# Filter by Example: Wiener Filter

Assume:

$$\hat{s}(t) = g(t) * [s(t) + n(t)]$$

where:

- $s(t)$  is original signal
- $n(t)$  is noise footprint
- $\hat{s}(t)$  is estimated signal
- $g(t)$  is Wiener Filter



# Filter by Example: Wiener Filter

Define Error:

$$e(t) = s(t + \alpha) - \hat{s}(t)$$

with  $\alpha$  being the delay. Thus:

$$e^2(t) = s^2(t + \alpha) - 2s(t + \alpha)\hat{s}(t) + \hat{s}^2(t)$$

(squared error)



# Filter by Example: Wiener Filter

Define Error:

$$e(t) = s(t + \alpha) - \hat{s}(t)$$

with  $\alpha$  being the delay. Thus:

$$e^2(t) = s^2(t + \alpha) - 2s(t + \alpha)\hat{s}(t) + \hat{s}^2(t)$$

(squared error)



# Filter by Example: Wiener Filter

Results in:

$$G(s(t)) = |X(s(t))|^2 / (|X(s(t))|^2 + |N(s(t))|^2)$$

where:

- $X(s(t))$  is the power spectrum of the signal,
- $s(t)$  and  $N(s(t))$  is the power spectrum of the noise, and
- $G(s(t))$  is the frequency-space Wiener filter.

Problem: Do we know  $N(s(t))$ ?

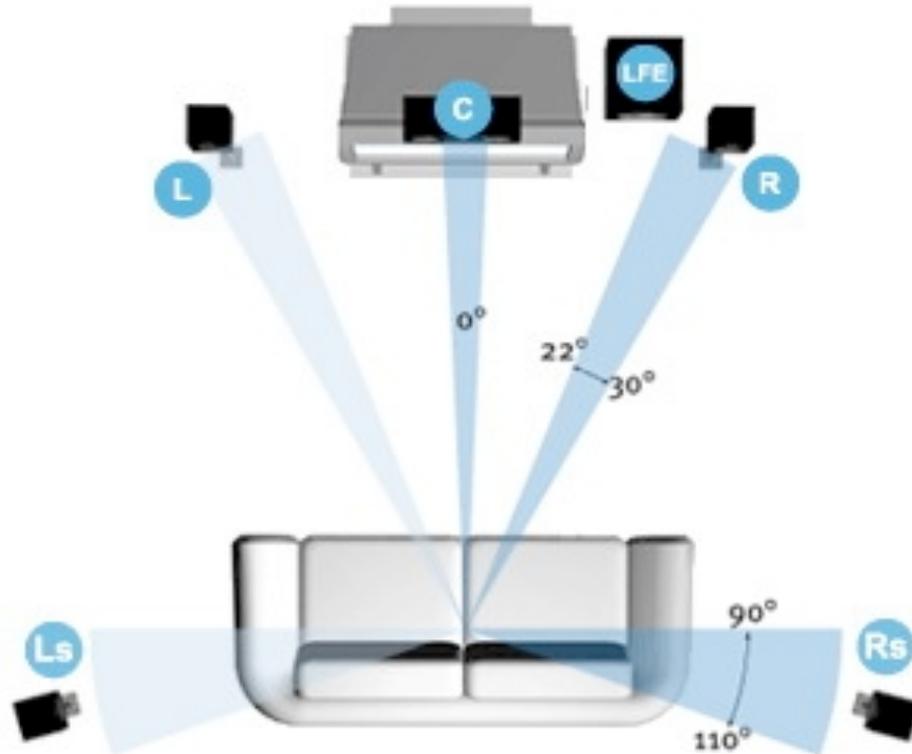


# Multichannel Audio

- Microphone Array Recordings popular with Speech Community
- Stereo popular since the 1960s.
- Most cameras have stereo microphones
- Most DVDs are encoded in Dolby Digital 5.1 and in Dolby Surround on Stereo Track



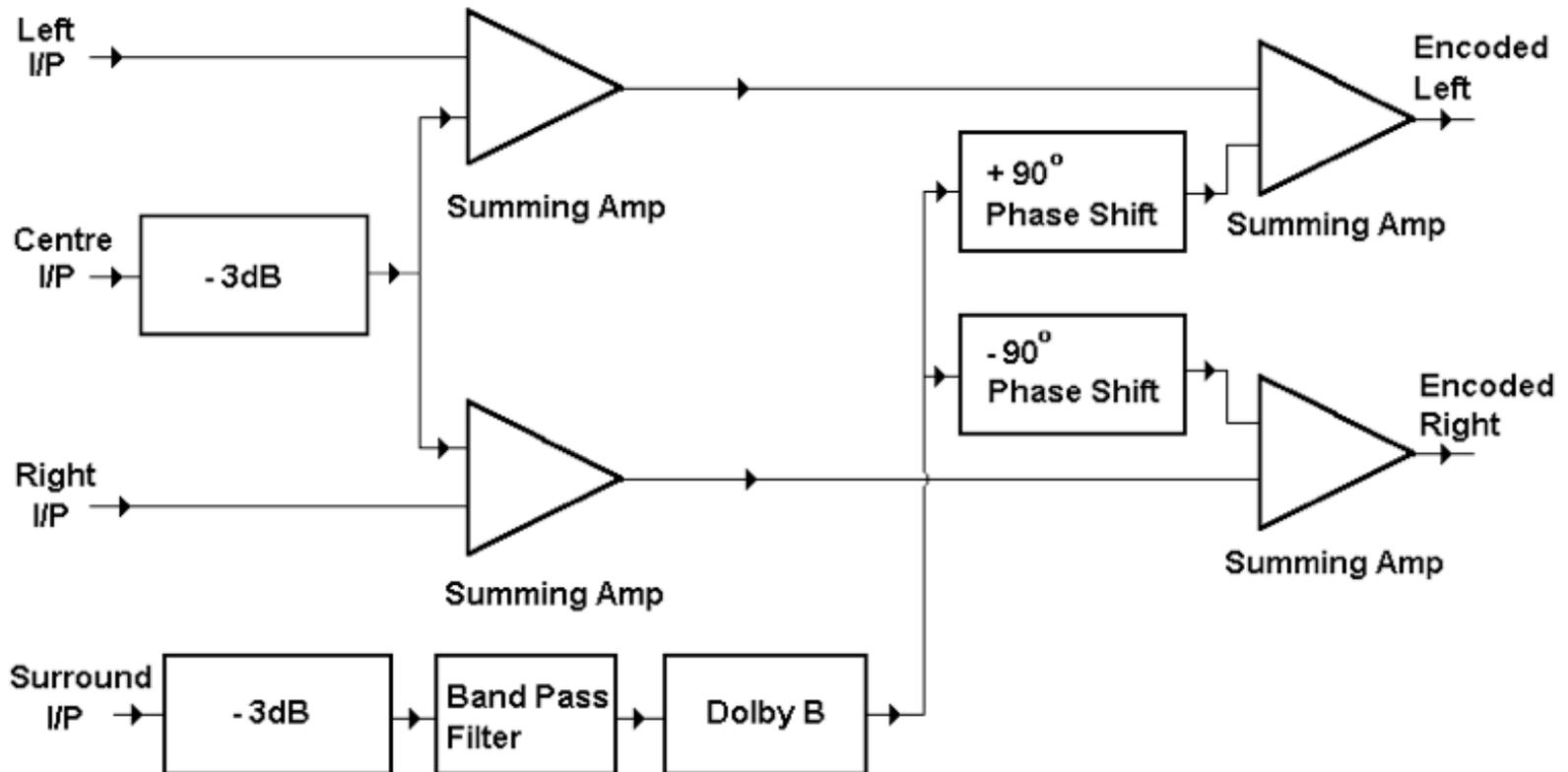
# Dolby Digital



Source: <http://www.aspecttv.co.uk/surround-sound-setup/>



# Dolby Surround





# How to Cope with Multiple Channels?

- Treat them individually (different channel=different content)
- Combine them, ideally while reducing noise
- Cross-Infer between channels
- Any combination of the above

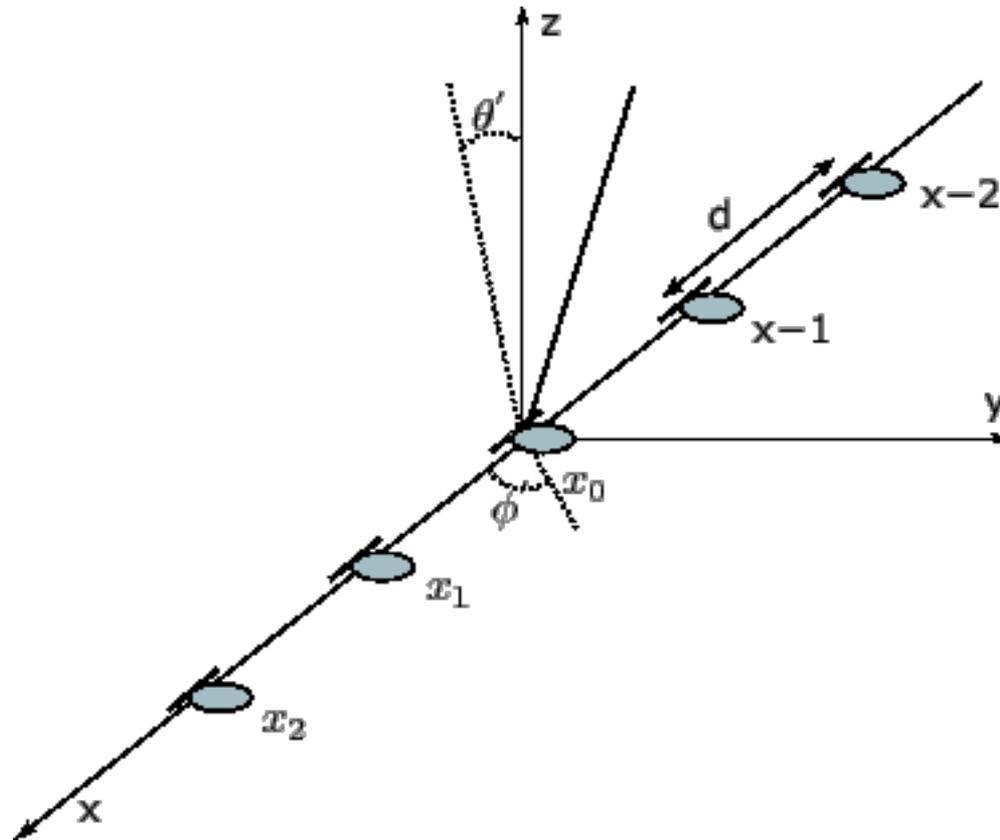


# Combining Channels

- Beamforming, two major techniques:
  - Delay-Sum
  - Frequency-Domain Beamformer



# Delay-Sum Beamforming



More Information: <http://www.xavieranguera.com/phdthesis/>



# Delay-Sum Beamforming

## Output:

- Sum of all channels (lower noise)
- Delay between microphones (directional signal)



# Some Basic Audio Features

- Energy (usually rms)
- Zero-Crossing Rate
- Entropy
- Pitch
- Voicedness/Unvoicedness (HNR)
- Long-Term Average Spectrum (LTAS)



# Energy

Energy is usually calculated as the root-mean square of a window of samples:

$$x_{\text{rms}} = \sqrt{\frac{1}{n} \sum_{i=1}^n x_i^2} = \sqrt{\frac{x_1^2 + x_2^2 + \dots + x_n^2}{n}}$$

- Most pre-valent basic feature
- Typical filter uses: Squelching
- For analysis: Is there audio at all?



# Zero-Crossing Rate

$$SC_{[m]} = \frac{1}{2} \sum_{n=m-N+1}^m |\text{sgn}(s[n]) - \text{sgn} s[n-1]|$$

Used among other things in overlapping speech detection, voiced/unvoiced estimation, music analysis



# Entropy

$$H(X) = - \sum_{i=1}^n p(x_i) \log p(x_i).$$

How noisy is the signal? Helps in many cases.



# Pitch

Most frequently used method is autocorrelation:

$$R[l, m] = \sum_{n=m-N+1}^m S[n]S[n-l]$$

Fails in many situations, computationally intensive.

Pitch Estimation is ongoing research!



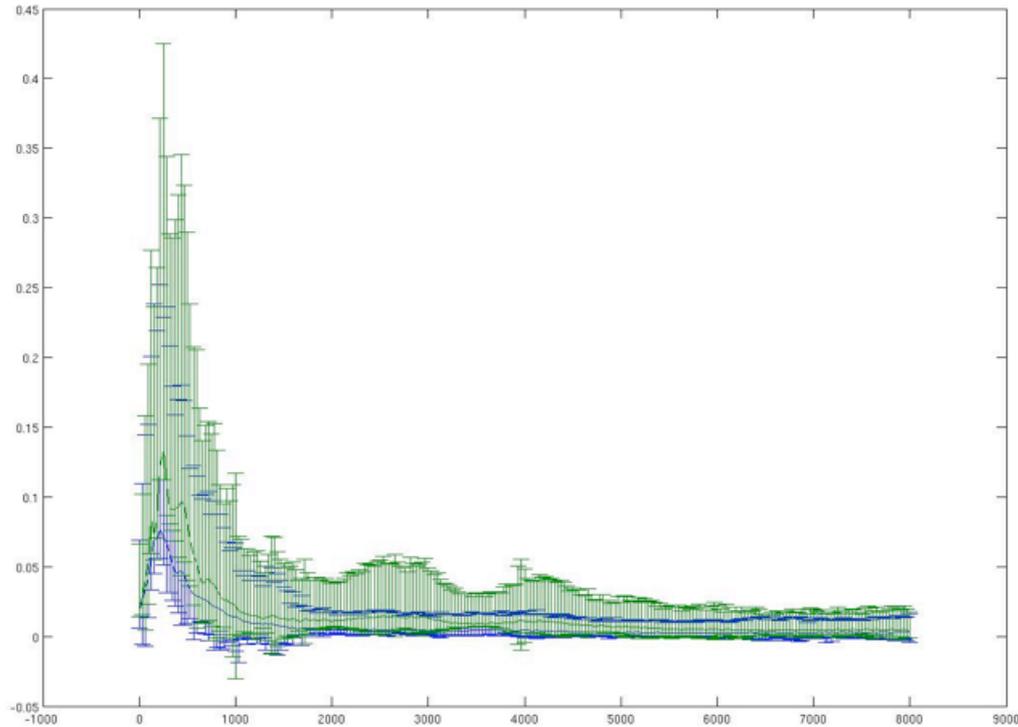
# Harmonic-to-Noise Ratio

$$HNR = \frac{v}{uv}$$

Used as indicator for type of audio (e.g. speech vs music, types of music), speaker age, and as a metric for quality distortion.



# Long-Term Average Spectrum

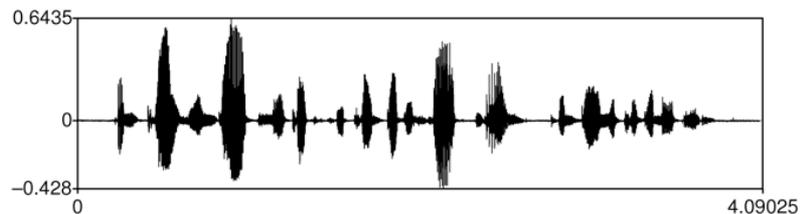


Often used as indicator for type of audio (e.g. speech vs music, types of music).



# Basic Audio Features

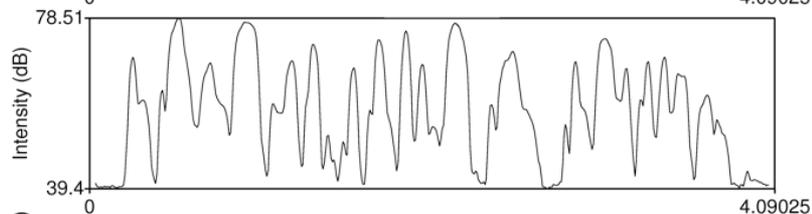
**A Speech Signal:**



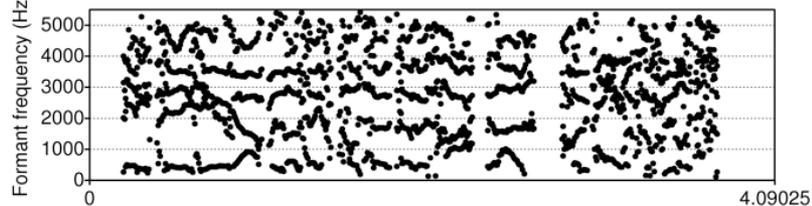
**Pitch:**



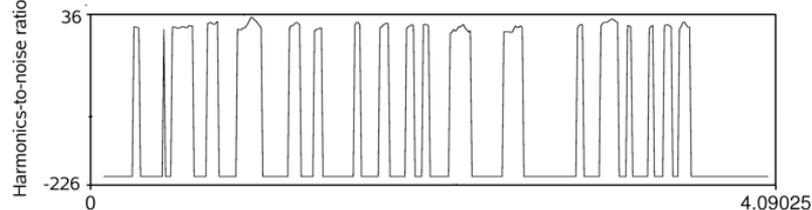
**Energy:**



**Formants:**



**HNR:**



Time (s)



# More on Features

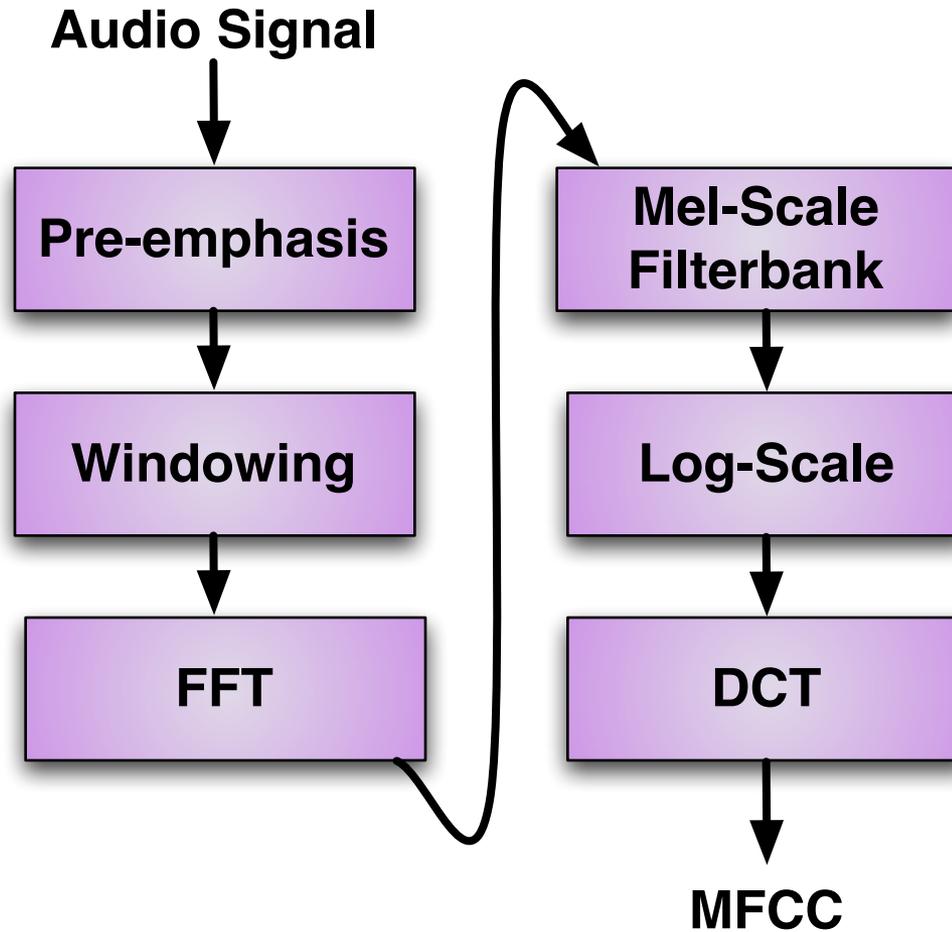
- Mel-Frequency-Scaled Coefficients (MFCC)

Other (not explained here):

- LPC (Linear Prediction Coefficients)
- PLP (Perceptual Linear Predictive) Features
- RASTA (see Morgan et al)
- MSG (Modulation Spectrogram)



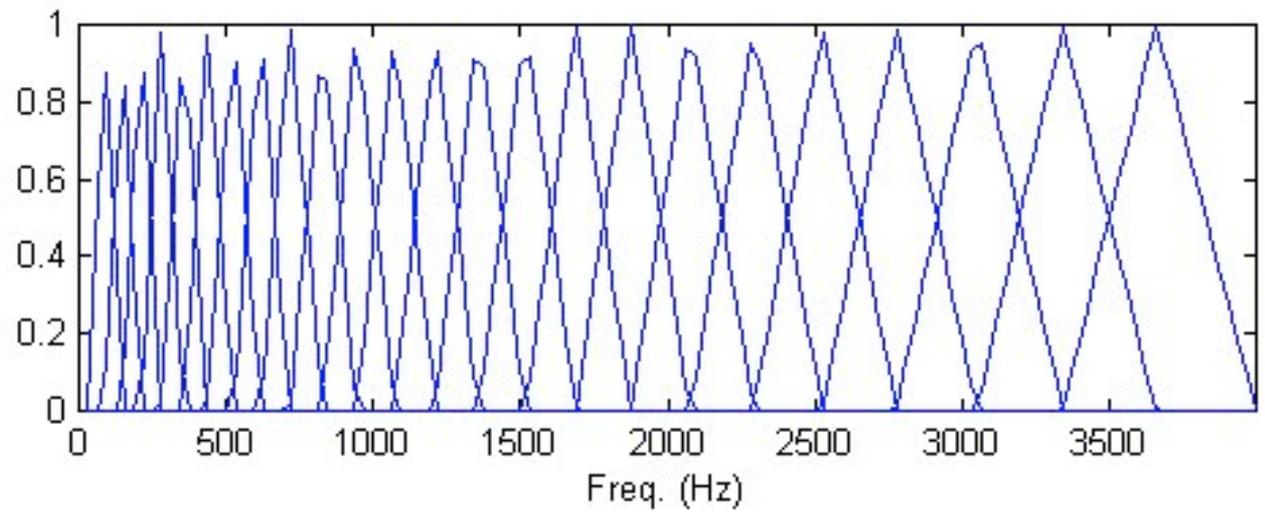
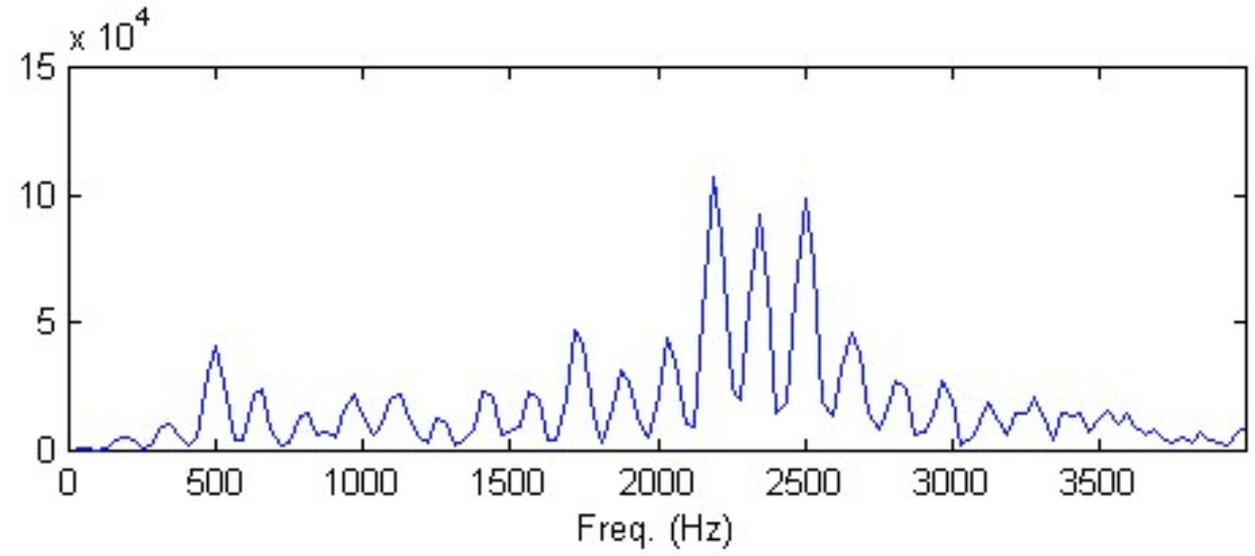
# MFCC: Idea



$$\text{power cepstrum of signal} = |\mathbf{F} \{ \log(|\mathbf{F} \{ \text{the signal} \}|^2) \}|^2$$

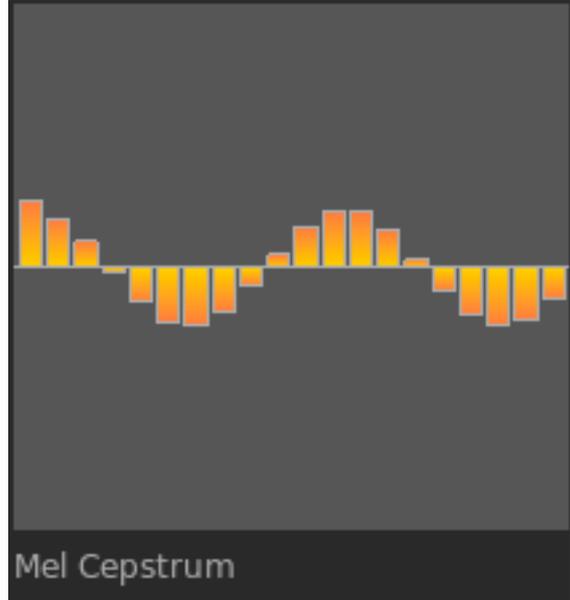
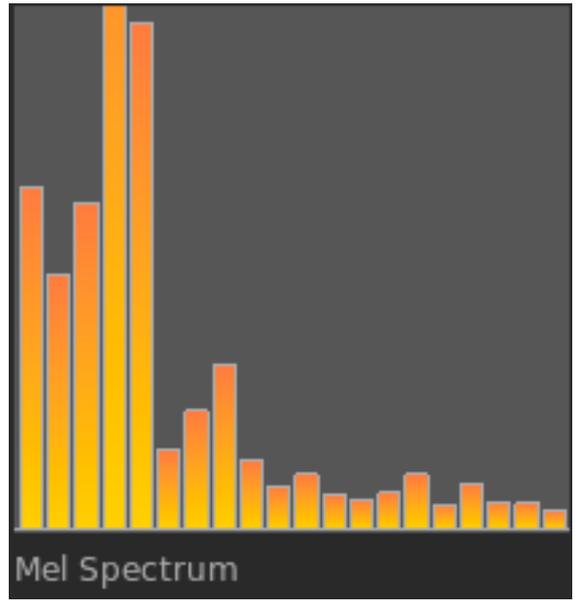
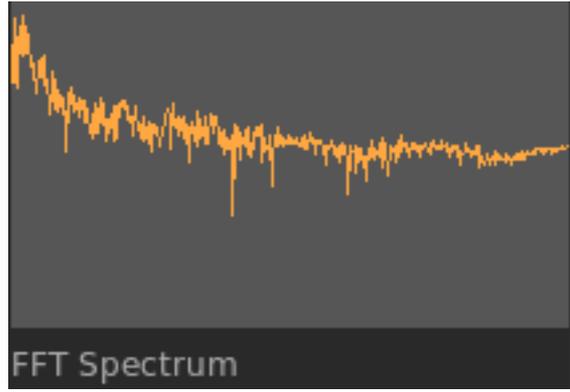


# MFCC: Mel Scale





# MFCC: Result





# MFCC Variants and Derivates

## Parameters:

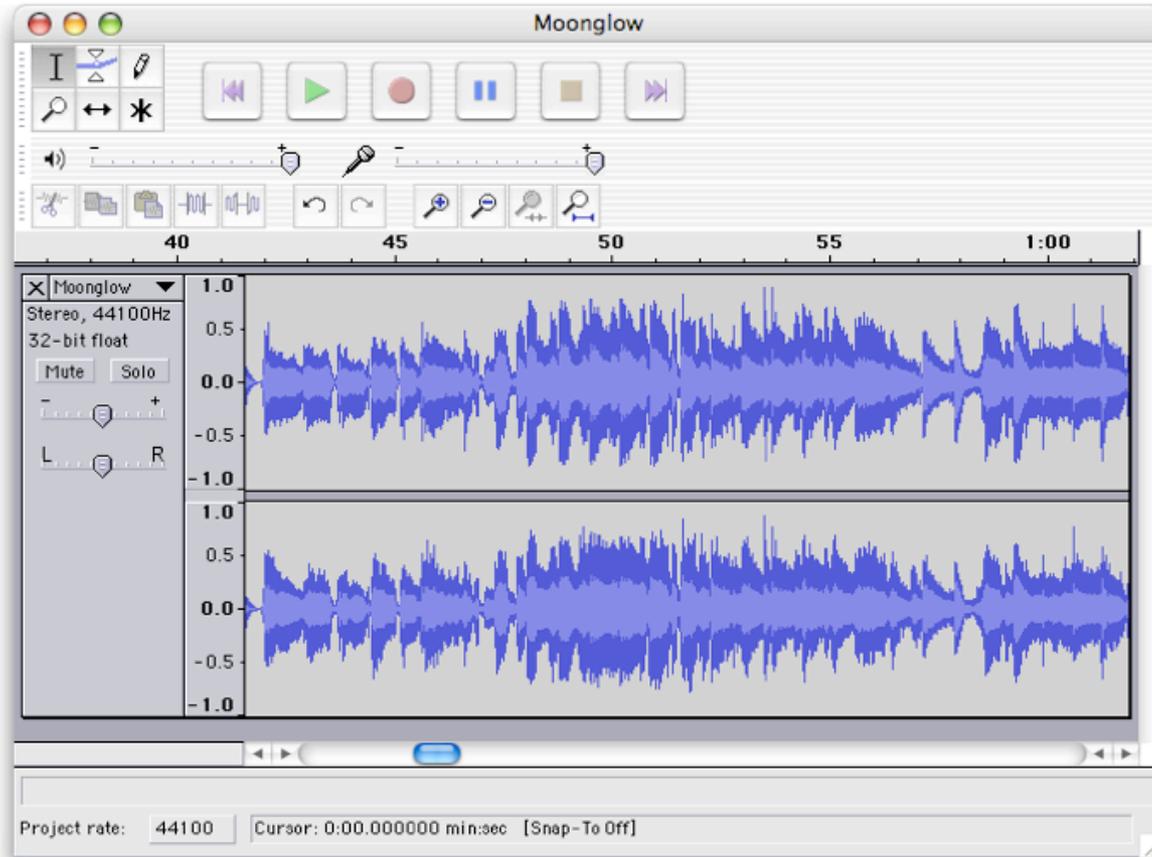
- MFCC12 (often used for ASR)
- MFCC19 (often used in speaker id, diarization)
- “delta”: coefficients subtracted (“first derivative”)
- “deltadelta”: “second derivative”
- Short term: Usually calculated on 10-50ms window

## Derivates:

- LFCC (no Mel scale)
- AMFCC (anti Mel scale)



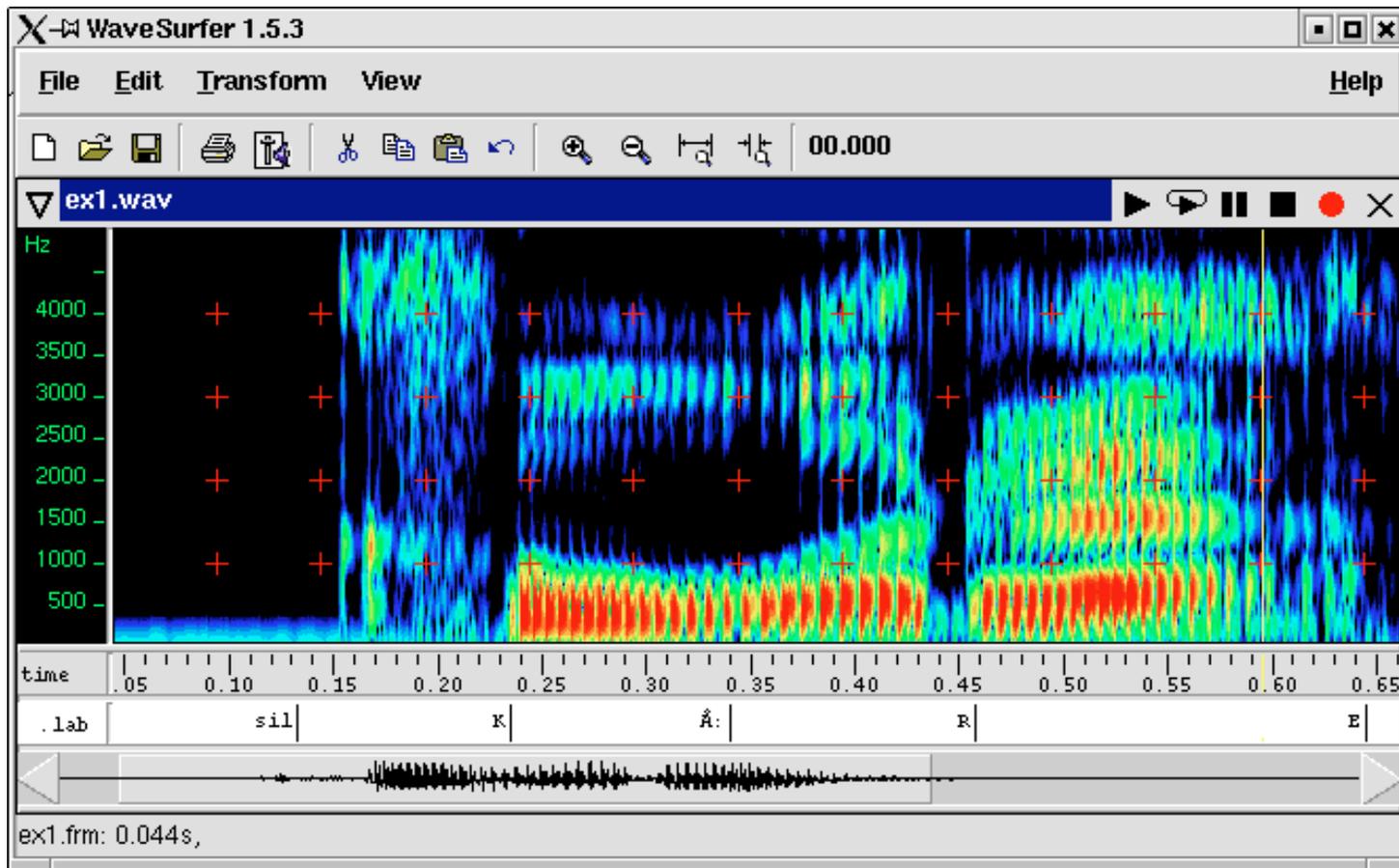
# Audacity



Open Source wave editor and filter:  
<http://audacity.sourceforge.net/>



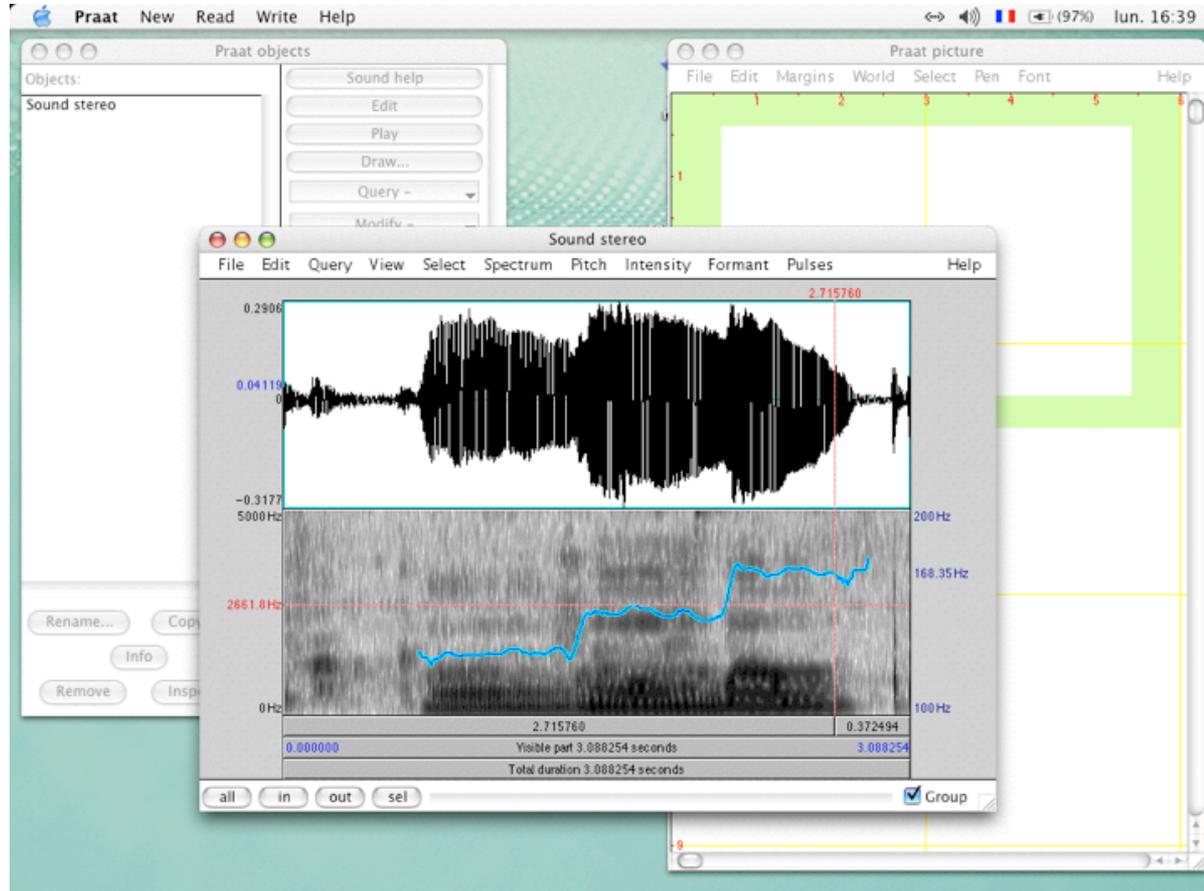
# Wavesurfer



Open Source wave editor and filter, specialized for speech:  
<http://www.speech.kth.se/wavesurfer/>



# Praat



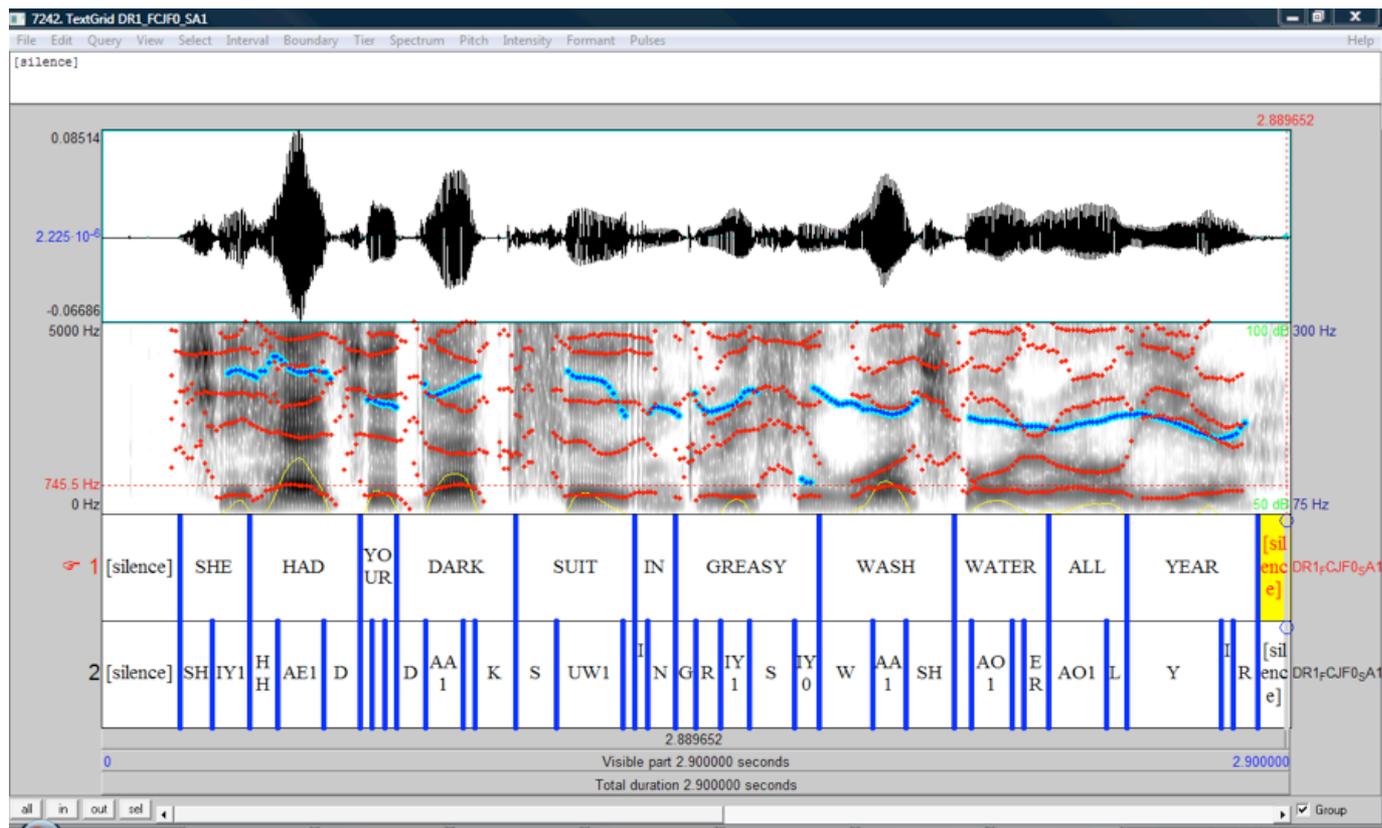
Open Source speech experimental toolkit  
<http://www.fon.hum.uva.nl/praat/>



# Other useful tools

- sox -- command-line based audio filter and converter: <http://sox.sourceforge.net/>
- ffmpeg -- command-line based audio and video converter <http://ffmpeg.org/>
- MPlayer (mencoder) -- open source video player and converter: <http://www.mplayerhq.hu/>

# More Tools: HTK



Open Source Speech Recognition Toolkit:  
<http://htk.eng.cam.ac.uk/>



# More Tools: A nice collection of them

Princeton SoundLab:

<http://soundlab.cs.princeton.edu/software/>



## Next Week

- More on Features
- Some Machine Learning